

M.Tech. (Computer Science) Dissertation Series

Reasoning About Knowledge and Probability

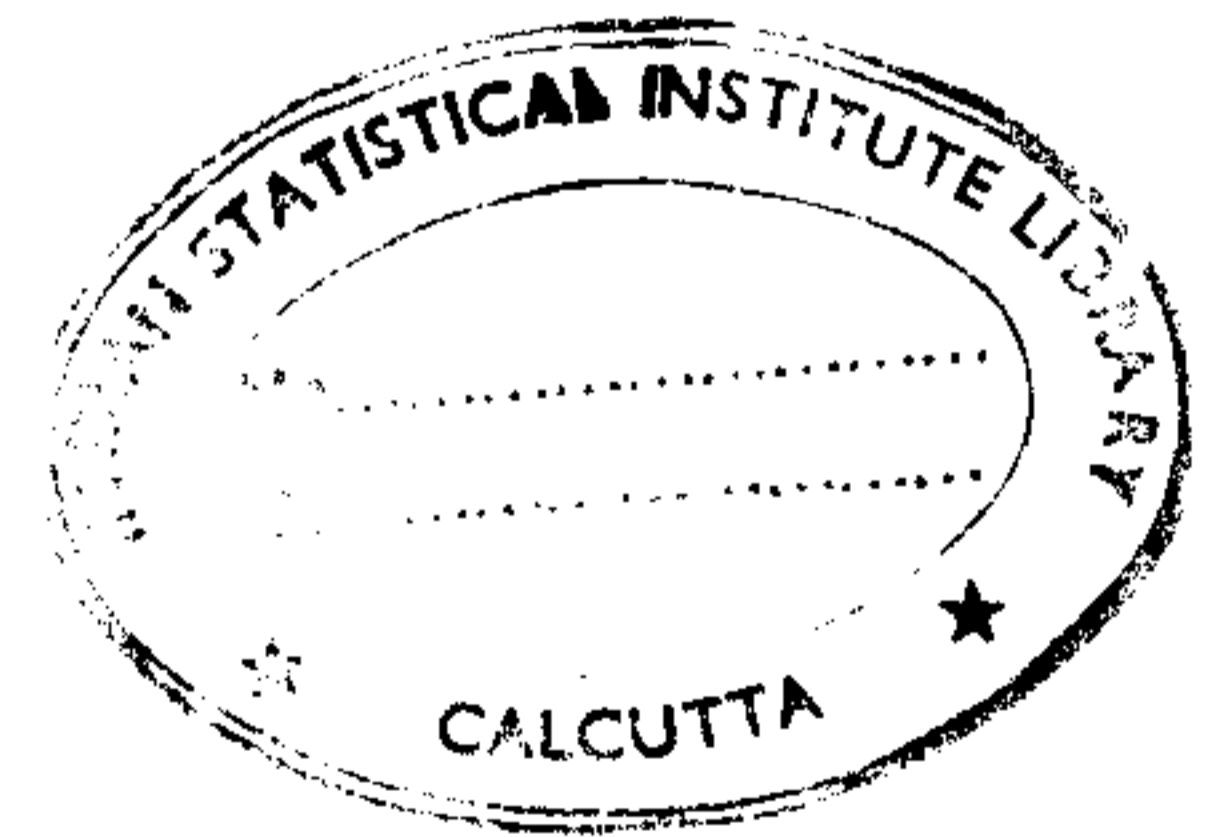
a dissertation submitted in partial fulfilment of the
requirements for the M. Tech. (Computer Science)
degree of the Indian Statistical Institute

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Certificate of Approval

This is to certify that the thesis entitled *Reasoning About Knowledge and Probability* submitted by *Rakesh Kumar Bhatia*, towards partial fulfillment of the requirement for ***M. Tech.*** in *Computer Science* degree of the *Indian Statistical Institute, Calcutta*, is an acceptable work for the award of the degree.

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Rakesh Kumar Bhatia

We have reviewed works done on Reasoning About Knowledge and Probability introduced by Ronald Fagin, Joseph Y. Halpern (IBM Almaden Research Centre, San Jose, California)

We allow explicit mentions of probabilities in formulas, so that our language has formulas that essentially says "according to agent i , formula ϕ holds with probability at least b ".

The language is powerful enough to allow reasoning about higher order probabilities as well as the explicit comparisons of the probabilities an agent places on distinct events. and on the basis of the results we have tried to give probability assignments to Linear Time Temporal Logic formulas.

Reasoning About Knowledge and Probability

Introduction

In many of the application areas for reasoning about knowledge, it is important to be able to reason about the probability of certain events as well as the knowledge of agents.

In the standard possible worlds model of knowledge, agent i knows a fact ϕ , written $K_i\phi$ in a world or state s , if ϕ is true in all the worlds the agent considers possible in world s .

We want to reason not only about agents knowledge, but also about the probability he places on certain events. In order to do this we extend the language. Typical formulas in the logic of Fagin et al. includes $w(\phi) \geq 2w(\psi)$ and $w(\phi) < \frac{1}{3}$, where ϕ and ψ are propositional formulas.

These formulas can be viewed as saying,

" ϕ is twice as probable as ψ " and
" ϕ has probability less than $\frac{1}{3}$ ".

In order to give semantics to such a language in the possible world framework, we assume that roughly speaking, at each state each agent has a probability on the worlds he considers possible. Then a formula such as $w_i(\phi) \geq 2w_i(\psi)$ is true at each state s if, according to agent i 's probability assignment at state s , the event ϕ is twice as probable as ψ .

The Standard Kripke structure for Knowledge and Probability

Syntax

P : non-empty set of propositional letters.

K_i : $1 \leq i \leq n$ Knowledge modalities

ω_i : probability modalities.

(behaviours distinct from K_i)
 $1 \leq i \leq n$.

Then Φ , the set of formulas is defined inductively as follows.

- Every member of P belongs to Φ .
- If ϕ_1 and ϕ_2 are formulas in Φ , then so are $\sim \phi_1$, $\phi_1 \vee \phi_2$, $K_i(\phi_1)$
- If $\phi_1, \phi_2, \dots, \phi_k$ are formulas in Φ , then so is

$$a_1 \omega_i(\phi_1) + \dots + a_k \omega_i(\phi_k) \geq b.$$

Semantics

$v: P \rightarrow \{T, F\}$ is a valuation

$V =$ set of all valuations

$(S, \Pi, \mathcal{K}_1, \mathcal{K}_2, \dots, \mathcal{K}_n)$ is a Kripke structure.

where $S = \{s_1, s_2, \dots, s_m\}$ are the set of worlds.

$\Pi: S \rightarrow V$, $\Pi(s)(p) = T$ or F
and \mathcal{K}_i is an equivalence relation on S .

for $s_i \in S$, $\mathcal{K}_i(s_j) =$ equivalence class of s_j under \mathcal{K}_i .

Probability Space

Probability space is a tuple $(\Omega, \mathcal{K}, \mu)$ where Ω is a set called the sample space, \mathcal{K} is a σ -algebra of subsets of Ω (i.e. a set of subsets containing Ω and closed under complementation and countable union) whose elements are called the measurable sets and a probability measure μ defined on the elements of \mathcal{K} .

μ does not assign probability to all subsets of Ω but only to the measurable sets. One natural way of attaching weight to every subsets of Ω is considering the inner measure μ_* , if

$A \subseteq \Omega$, then

$$\mu_*(A) = \sup \{ \mu(B) \mid B \subseteq A, B \in \mathcal{K} \}.$$

Kripke Structure for Knowledge and Probability

Model: $M = (S, \pi, \mathcal{K}_1, \mathcal{K}_2, \dots, \mathcal{K}_n, P)$

where

$P: \{1, \dots, n\} \times S \rightarrow$ probability space

$\mathcal{P}_{i,s} = (S_{i,s}, \mathcal{K}_{i,s}, \mathcal{U}_{i,s})$

n : number of agents.

Interpretation

- ① $(M, s) \models p$ iff $\pi(s)(p) = T$
- ② $(M, s) \models \sim \phi$ iff $(M, s) \not\models \phi$
- ③ $(M, s) \models \phi_1 \vee \phi_2$ iff
 $(M, s) \models \phi_1$ or $(M, s) \models \phi_2$
- ④ $(M, s) \models K_i \phi$ iff
 $(M, t) \models \phi \quad \forall t \in \mathcal{K}_i(s)$
- ⑤ $(M, s) \models w_i(\phi) \geq b$ iff
 $c \geq b$ where
 $c = \mathcal{U}_{i,s}(\{t \in S_{i,s} \mid (M, t) \models \phi\})$

$$\textcircled{6} \quad (M, s) \models a_1 w_i(\phi_1) + a_2 w_i(\phi_2) + \dots + a_k w_i(\phi_k) \geq b$$

iff $c \geq b$ where

$$c = a_1 (\mu_{i,s})_* (\{t \in S_{i,s} \mid (M, t) \models \phi_1\}) + \dots + a_k (\mu_{i,s})_* (\{t \in S_{i,s} \mid (M, t) \models \phi_k\}).$$

Example.

Suppose there are two agents. Agent 2 has an input bit either 0 or 1. He then tosses a fair coin, and perform an action a if the coin toss agrees with the input bit, i.e. if the coin toss lands heads and the input bit is 1 or if the coin lands tails and the input bit is 0. It is assumed that agent 1 never learns agent 2's input bit or the outcome of his coin toss.

An easy argument shows that according to Agent 2 who knows the input bit, the probability (before he tosses the coin) of performing action a is $\frac{1}{2}$. There is also a reasonable argument to show that, even according to agent 1 (who does not know the input bit), the probability that action will be performed is $\frac{1}{2}$.

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Now we try to capture this argument in our formal system.

$$b \in \{0, 1\}$$

$$\text{coin toss } (t) \in \{H, T\}$$

Action a will be performed if

$$b = 1, t = H \quad \text{or}$$

$$b = 0, t = T.$$

$$S = \{s_1, s_2, s_3, s_4\}$$

Where $s_1 = (1, H)$

$$s_2 = (1, T)$$

$$s_3 = (0, H)$$

$$s_4 = (0, T)$$

A: Action a is performed by agent 2.

H: coin landed head

T: coin landed tail

B_0 : bit is 0

B_1 : bit is 1

$$M = (S, \pi, \mathcal{K}_1, \mathcal{K}_2, P)$$

Where $\mathcal{K}_1 = \{s_1, s_2, s_3, s_4\}$

$$\mathcal{K}_2 = \{\{s_1\}, \{s_2\}, \{s_3\}, \{s_4\}\}$$

	A	H	T	B_0	B_1
$\pi(s_1)$	t	t	f	f	t
$\pi(s_2)$	f	f	t	f	t
$\pi(s_3)$	f	t	f	t	f
$\pi(s_4)$	t	f	t	t	f

What should agent 1's probability assignment be?

There are three possible answers to this question.

① We can associate with each state the sample space consisting of all four states.

i.e. $S_{1,s_i} = \{s_1, s_2, s_3, s_4\}$
for $1 \leq i \leq 4$.

Because there is no probability "the input bit is 0" ("respectively input bit is 1"), the candidates for measurable sets are $\{s_1, s_3\}$ ("the coin landed head") and $\{s_2, s_4\}$ ("the coin landed tail") i.e. if we take the Kripke structure M_0 then we have,

$$P_{1,s_1} = P_{1,s_2} = P_{1,s_3} = P_{1,s_4}$$

and $\mathcal{K}_{1,s_i} = \left\{ \begin{array}{l} \{s_1, s_3\}, \{s_2, s_4\}, \emptyset, \\ \{s_1, s_2, s_3, s_4\} \end{array} \right\}$.

where $1 \leq i \leq 4$.

$$\mu_{1,s_i}(\{s_1, s_3\}) = \frac{1}{2} \quad \forall i$$

$$\mu_{1,s_i}(\{s_2, s_4\}) = \frac{1}{2}$$

Here the events $\{s_1\}$ and $\{s_2\}$ cannot both be measurable, for then the event $\{s_1, s_2\}$ which corresponds to "input bit is 1" would also be measurable.

$$\textcircled{2} \quad P_{1, s_1} = P_{1, s_2} \quad (\text{input bit is 1})$$

where

$$S_{1, s_i} = \{s_1, s_2\}$$

$$\mathcal{K}_{1, s_i} = \{\{s_1\}, \{s_2\}, \emptyset, \{s_1, s_2\}\}$$

$$\mu_{1, s_i}(\{s_1\}) = \mu_{1, s_i}(\{s_2\}) = \frac{1}{2} \\ 1 \leq i \leq 2$$

$$P_{1, s_3} = P_{1, s_4} \quad (\text{input bit is 0})$$

where

$$S_{1, s_i} = \{s_3, s_4\}$$

$$\mathcal{K}_{1, s_i} = \{\{s_3\}, \{s_4\}, \emptyset, \{s_3, s_4\}\}$$

$$\mu_{1, s_i}(\{s_3\}) = \mu_{1, s_i}(\{s_4\}) = \frac{1}{2} \\ 3 \leq i \leq 4$$

We call the above structure M_4 .

$$\textcircled{3} \quad S_{1, s_1} = \{s_1\}$$

$$S_{1, s_2} = \{s_2\}$$

$$S_{1, s_3} = \{s_3\}$$

$$S_{1, s_4} = \{s_4\}$$

$$\begin{aligned} \mu_{1, s_1}(\{s_1\}) &= \mu_{1, s_2}(\{s_2\}) = \mu_{1, s_3}(\{s_3\}) \\ &= \mu_{1, s_4}(\{s_4\}) = 1 \end{aligned}$$

The above structure is M_2 .

Now it is easy to check that for each s in S .

$$(M_1, s) \models K_1 (w_1(A) \geq \frac{1}{2})$$

First we show that

$$(M_0, s) \not\models K_1 (w_1(A) \geq \frac{1}{2})$$

$$(M_0, s) \models K_1 (w_1(A) \geq \frac{1}{2})$$

iff

$$(M_0, t) \models w_1(A) \geq \frac{1}{2} \quad \forall t \in K_1(s)$$

Now

$$(M_0, s_1) \models w_1(A) \geq \frac{1}{2}$$

iff

$$\mu_{1, s_1}^* (\{t \in S_{1, s_1} \mid (M_0, t) \models A\}) \geq \frac{1}{2}$$

i.e. $\mu_{1, s_1}^* (\{s_1, s_4\}) \geq \frac{1}{2}$

since A is true in s_1 and s_4 only.

$$\mu_{1, s_1}^* (\{s_1, s_4\}) = \mu_{1, s_1} (\emptyset) = 0$$

since the only measurable set contained in $\{s_1, s_4\}$ is \emptyset .

$$\therefore (M_0, s_1) \not\models K_1 (w_1(A) \geq \frac{1}{2})$$

Now since,

$$P_{1,s_1} = P_{1,s_2} = P_{1,s_3} = P_{1,s_4}$$

There does not exist any state s , such that

$$(M_0, s) \models K_1 (w_1(A) \gg \frac{1}{2})$$

Now we show that,

$$(M_1, s) \models K_1 (w_1(A) \gg \frac{1}{2}) \text{ --- } \textcircled{1}$$

$\textcircled{1}$ holds iff

$$(M_1, t) \models w_1(A) \gg \frac{1}{2} \quad \forall t \text{ in } \mathcal{K}_1(s)$$

$$(M_1, s_1) \models w_1(A) \gg \frac{1}{2}$$

iff.

$$\mu_{1,s_1}^* (\{y \in S_{1,s_1} / (M_1, y) \models A\}) \geq \frac{1}{2}$$

i.e

$$\mu_{1,s_1}^* (\{s_1, s_4\}) \geq \frac{1}{2}$$

$$\text{Now } \mu_{1,s_1}^* (\{s_1, s_4\}) = \mu_{1,s_1} (\{s_1\})$$

$$= \frac{1}{2}$$

$$\therefore (M_1, s_1) \models w_1(A) \gg \frac{1}{2} \quad (\text{since } s_1 \text{ is measurable})$$

Since $P_{1,s_1} = P_{1,s_2}$
 $(M_{1,s_2}) \models \omega_1(A) \gg \frac{1}{2}$.

Similarly we can show that

$$(M_{1,s_3}) \models \omega_1(A) \gg \frac{1}{2}.$$

$$(M_{1,s_4}) \models \omega_1(A) \gg \frac{1}{2}.$$

$$\therefore (M_{1,s_i}) \models K_1(\omega_1(A) \gg \frac{1}{2})$$

where $1 \leq i \leq 4$.

because

$$(M_{1,s_i}) \models K_1(\omega_1(A) \gg \frac{1}{2})$$

iff

$$(M_{1,t}) \models \omega_1(A) \gg \frac{1}{2} \quad \forall t \text{ in } \mathbb{K} \mathcal{K}_1(s_i)$$

$$\text{Now } \mathcal{K}_1(s_1) = \mathcal{K}_1(s_2) = \mathcal{K}_1(s_3) = \mathcal{K}_1(s_4)$$

$$= \{s_1, s_2, s_3, s_4\}.$$

The above argument holds in any state.

Now we show that

$$(M_2, s) \not\models K_1 (w_1(A) \geq \frac{1}{2})$$

$$(M_2, s_1) \models K_1 (w_1(A) \geq \frac{1}{2})$$

iff

$$(M_2, t) \models w_1(A) \geq \frac{1}{2} \quad \forall t \in \mathcal{K}_1(s_1).$$

$$\text{Now } \mathcal{K}_1(s_1) = \{s_1, s_2, s_3, s_4\}$$

$$(M_2, s_1) \models w_1(A) \geq \frac{1}{2}$$

$$\text{iff } \mu_{1, s_1}^* (\{t \in S_{1, s_1} \mid (M_2, t) \models A\}) \geq \frac{1}{2}.$$

$$\text{i.e. } \mu_{1, s_1}^* (\{s_1\}) \geq \frac{1}{2}.$$

$$\text{But } \mu_{1, s_1} (\{s_1\}) = 1$$

$$\therefore (M_2, s_1) \models w_1(A) \geq \frac{1}{2} \quad \text{holds.}$$

Now

$$(M_2, s_2) \not\models w_1(A) \geq \frac{1}{2}.$$

iff

$$\mu_{1, s_2}^* (\{t \in S_{1, s_2} \mid (M_2, t) \models A\}) \geq \frac{1}{2}.$$

$$\text{i.e. } \mu_{1, s_2}^* (\{t \in s_2 \mid (M_2, t) \models A\}) \geq \frac{1}{2}.$$

$$\text{i.e. } \mu_{1, s_2}^* (\emptyset) \geq \frac{1}{2}.$$

But

$$\mu_{1, s_2}^* (\emptyset) = 0.$$

$$\therefore (M_2, s_2) \not\models w_1(A) \geq \frac{1}{2}.$$

[since A is true
in s_2 and
 s_4 only].

Hence

$$(M_2, s_1) \not\models K_1(\omega_1(A) \geq \frac{1}{2})$$

$$\text{Since } \mathcal{K}_1(s_1) = \mathcal{K}_1(s_2) = \mathcal{K}_1(s_3) = \mathcal{K}_1(s_4) \\ = \{s_1, s_2, s_3, s_4\}$$

there does not exist any state s in S such that

$$(M_2, s) \models K_1(\omega_1(A) \geq \frac{1}{2})$$

Further, we can show,

for every state $s \in S$, we have

$$(M_2, s) \models K_1((\omega_1(A)=1) \vee (\omega_1(A)=0))$$

The above statement holds iff

$$(M_2, t) \models (\omega_1(A)=1 \vee \omega_1(A)=0) \quad \forall t \in \mathcal{K}_1(s)$$

$$(M_2, s_1) \models (\omega_1(A)=1 \vee \omega_1(A)=0) \\ \text{iff}$$

$$(M_2, s_1) \models \omega_1(A)=1$$

$$\vee (M_2, s_1) \models \omega_1(A)=0$$

Now

$$(M_2, s_1) \models \omega_1(A)=1$$

iff

$$\mu_{1, s_1} * (\{t \in S_{1, s_1} \mid (M_2, t) \models A\}) = 1$$

i.e.

$$\mu_{1, s_1^*}(\{s_1\}) = 1.$$

But

$$\mu_{1, s_1^*}(\{s_1\}) = 1$$

[Since $\{s_1\}$ is the only measurable set in S_{1, s_1}].

Now since A is false in state s_2 and s_3 we have,

$$(M_2, s_2) \models w_1(A) = 0$$

$$\text{and } (M_2, s_3) \models w_1(A) = 0.$$

Again since A is true in s_4 .

$$(M_2, s_4) \models w_1(A) = 1.$$

Hence

$$(M_2, s_1) \models K_1((w_1(A) = 1) \vee (w_1(A) = 0)).$$

Now since

$$Pr_1(s_1) = Pr_1(s_2) = Pr_1(s_3) = Pr_1(s_4).$$

we have

$$(M_2, s) \models K_1((w_1(A) = 1) \vee (w_1(A) = 0))$$

for each s in S .

Finally in M_0 , the event A is not measurable, nor does it contain any non-empty measurable sets. Thus we have,

$$(M_0, \mathcal{F}) \models K_1 (w_1(A) = 0)$$

[The proof is similar to the above proofs].

FEW PROPERTIES

① We turn the following condition
consistent (CONS)

For all i and s if

$$P_{i,s} = (S_{i,s}, K_{i,s}, M_{i,s})$$

then $S_{i,s} \subseteq K_i(s)$.

Consistency does not imply that
 $s \in S_{i,s}$; an agent is not required
to view the state that he is in
as one of the set of states in his
probability space.

② In the context of Kripke structure
for knowledge and probability, having
an objective probability assignment
corresponds to the following condition

OBJ: $P_{i,s} = P_{j,s} \quad \forall i, j \text{ and } s.$

The above property can also be termed
as.

AGENT INDEPENDENT PROBABILITY
DISTRIBUTION.

③ The following property is called
SDP (state determined property)

For all i and s , and t if $t \in \mathcal{K}_i(s)$
then $\mathcal{P}_{i,s} = \mathcal{P}_{i,t}$.

④ Formally we say uniformity holds
if

For all i, s and t if
 $\mathcal{P}_{i,s} = (S_{i,s}, \mathcal{K}_{i,s}, \mathcal{M}_{i,s})$
and $t \in S_{i,s}$, then
 $\mathcal{P}_{i,t} = \mathcal{P}_{i,s}$

⑤ We say that formulas define
measurable sets in M if

MEAS: For all i and s and for
every formula ϕ , the set

$$S_{i,s}(\phi) \in \mathcal{K}_{i,s}$$

$$\text{where } S_{i,s}(\phi) = \{t \in S_{i,s} \mid (M, t) \models \phi\}$$

Let $PMEAS$ be the property which says that all primitive propositions define measurable sets.

Lemma If M is a structure satisfying $CONS$, OBJ , $UNIF$ and $PMEAS$, then M satisfies $MEAS$.

PROOF: The proof is by induction on the structure of formulae.

Base: Since $PMEAS$ holds, all primitive propositions define measurable sets.

suppose $S_{i,s}(\phi_1) \in \mathcal{K}_{i,s}$ and

$S_{i,s}(\phi_2) \in \mathcal{K}_{i,s}$

then $S_{i,s}(\phi_1 \vee \phi_2) \in \mathcal{K}_{i,s}$

and $S_{i,s}(\sim\phi_1) \in \mathcal{K}_{i,s}$.

[since the set of measurable sets are closed countable union and complementation]

Now we prove that

$$S_{i,s}(\omega_i(\phi) \gg b) \in \mathcal{K}_{i,s}$$

$$S_{i,s}(\omega_i(\phi) \gg b)$$

$$= (\{t \in S_{i,s} \mid (M,t) \models \omega_i(\phi) \gg b\})$$

Suppose there is a state t in $S_{i,s}$
s.t.

$$(M,t) \models \omega_i(\phi) \gg b.$$

i.e.

$$\mathcal{U}_{i,t}^* (\{y \in S_{i,t} \mid (M,y) \models \phi\}) \gg b.$$

Since $t \in S_{i,s}$. $P_{i,t} = P_{i,s}$ by UNIF.

Hence

$$\mathcal{U}_{i,t}^* (\{y \in S_{i,t} \mid (M,y) \models \phi\}) \gg b.$$

can be written as.

$$\mathcal{U}_{i,s}^* (\{y \in S_{i,s} \mid (M,y) \models \phi\}) \gg b.$$

and so is either identically true
or false for all $t \in S_{i,s}$

i.e. either $S_{i,s}(w_i(\emptyset) \gg b)$ is \emptyset or $S_{i,s}$ and hence in both the case $S_{i,s}(w_i(\emptyset) \gg b)$ is measurable.

Now we have to prove that

$$S_{i,s}(K_j \emptyset) \in \mathcal{K}_{i,s}.$$

$$S_{i,s}(K_j \emptyset) = (\{y \in S_{i,s} \mid (M_i, y) \in K_j \emptyset\})$$

Let $y_i \in S_{i,s}$ be such that

$$(M_i, y_i) \in K_j \emptyset$$

i.e. $(M_i, x) \in \emptyset \quad \forall x \in K_j(y_i)$

Now since objectivity and uniformity holds, all the agents will have the same probability distribution in a particular state, and in all the states of $S_{i,s}$, agent i will have the same probability distribution.

By combining these two facts we can say that in all the states of $S_{i,s}$ agent i and agent j will have the same probability distribution.

Now since

$$(M, \gamma_1) \vDash K_j \emptyset$$

$$\text{i.e. } (M, t) \vDash \emptyset \quad \forall t \in \mathcal{K}_j(\gamma_1).$$

This does not imply.

$$(M, \gamma_2) \vDash K_j \emptyset$$

$$\text{i.e. } (M, t) \vDash \emptyset \quad \forall t \in \mathcal{K}_j(\gamma_2)$$

where $\gamma_2 \in S_{i, s}$.

i.e. if $S_{j, \gamma_1} = S_{j, \gamma_2}$ [since $P_{j, \gamma_1} = P_{j, \gamma_2}$]
 this does not imply

$$\text{if } (M, \gamma_1) \vDash K_j \emptyset$$

Then also $(M, \gamma_2) \vDash K_j \emptyset$.

~~Hence I think the above lemma is not correct.~~

[The above lemma was given by Ronald Fagin, Joseph Y Halpern in their paper named

Reasoning about Knowledge and Probability]

Suppose

$y_1 \in S_{i,s}$ be such that

$$(M, y_1) \models K_j \phi$$

$$\text{i.e. } (M, t) \models \phi \quad \forall \phi \in \mathcal{L}_G(y_1)$$

Then we have to prove that if

$$y_2 \in S_{i,s}$$

$$\text{then } (M, y_2) \models K_j \phi$$

$$\text{i.e. } (M, t) \models \phi \quad \forall \phi \in \mathcal{L}_G(y_2)$$

Now since uniformity holds

$$P_{i,s} = P_{i,y_1} = P_{i,y_2}$$

$$\text{i.e. } S_{i,s,y_1} = S_{i,y_2}$$

Since objectivity holds.

$$P_{i,y_1} = P_{j,y_1} \quad \text{and} \quad P_{i,y_2} = P_{j,y_2}$$

$$\text{i.e. } S_{i,y_1} = S_{j,y_1} \quad \text{and} \quad S_{i,y_2} = S_{j,y_2}$$

$$\text{i.e. } S_{j,y_1} = S_{j,y_2}$$

Now if $S_{j,y_1} = \mathcal{L}_G(y_1)$ and

$$S_{j,y_2} = \mathcal{L}_G(y_2)$$

then $\mathcal{L}_G(y_1) = \mathcal{L}_G(y_2)$

Hence

the above lemma holds if

$S_{i,s} = \mathcal{L}_i(s)$ for each agent i
and each state s .

Millers Principle

$$w_i(\emptyset) \gg_b w_i(w_i(\emptyset) \gg_b)$$

uniformity implies above axiom.

proof: $w_i(\emptyset) \gg_b$ is either true in state s or false in state s .
suppose it is false in state s .

i.e.

$$(M, s) \not\models w_i(\emptyset) \gg_b. \quad \text{--- (I)}$$

Then we have

$$(M, s) \models w_i(w_i(\emptyset) \gg_b) = 0. \quad \text{--- (II)}$$

Let us assume that the statement

(II) is false,

i.e. there exist a state $y \in S_{i,s}$
s.t.

$$(M, y) \models w_i(\emptyset) \gg_b.$$

i.e.

$$u_{i,y}(\{t \in S_{i,y} \mid (M, t) \models \emptyset\}) \gg_b.$$

Now since uniformity holds, agent i will have the same probability distribution in all the states of $S_{i,s}$.

∴

$$\mu_{i,s}^* (\{ t \in S_{i,s} / (M,t) \models \emptyset \}) \geq b$$

i.e.

$$(M,s) \models w_i(\emptyset) \geq b$$

which is a contradiction to the statement ①.

∴ ② holds.

and hence

$$(M,s) \models w_i(\emptyset) \geq 0$$

Now suppose,

$$(M,s) \models w_i(\emptyset) > b$$

Then we have

$$(M,s) \models w_i(w_i(\emptyset) > b) = 1$$

because

$$(M,s) \models w_i(\emptyset) \geq b$$

iff

$$\mu_{i,s}^* (\{ t \in S_{i,s} / (M,t) \models \emptyset \}) \geq b$$

Now since uniformity holds.

$$\mu_{i,y}^* (\{ t \in S_{i,y} / (M,t) \models \emptyset \}) \geq b \quad \forall y \in S_{i,s}$$

$$\therefore (M,s) \models w_i(w_i(\emptyset) > b) = 1$$

i.e. $(M,s) \models w_i(\emptyset) \geq b$ which holds.

Hence the proof.

We can also capture some of the assumptions we made about the system axiomatically.

① CONS. corresponds to the axiom

$$K_i \phi \Rightarrow (w_i(\phi) = 1)$$

First we prove that if

$$(M, s) \models K_i \phi$$

then $(M, s) \models w_i(\phi) = 1$

$(M, s) \models w_i(\phi) = 1$
iff.

$$\mu_{i,s}(\{t \in S_{i,s} \mid (M,t) \models \phi\}) = 1$$

Now since $S_{i,s} \subseteq \mathcal{K}_i(s)$ and

$(M, s) \models K_i \phi$.

ϕ must be true in all the states of $S_{i,s}$.

i.e.
$$\mu_{i,s}(\{t \in S_{i,s} \mid (M,t) \models \phi\})$$

$$= \mu_{i,s}(\{S_{i,s}\}) = 1.$$

$$\therefore (M, s) \models w_i(\phi) = 1.$$

Now we prove if

$(M, s) \models Ki\phi \Rightarrow (wi(\phi) = 1)$ for any

$s \in S$, then

CONS. must hold in M .

Now here if ϕ is true in all the states of $Ki(s)$, then ϕ is true in all the states of S_i, s .

i.e. There does not exist any state $y \in S$ such that ϕ_y is true in all the states of $Ki(y)$, but ϕ is not true at least in one state of S_i, y .

Hence $S_i, s \subseteq Ki(s) \quad \forall s \in S$.

i.e. CONS holds in M .

② OBJ corresponds to the axiom:

$$(a_1 w_i(\phi_1) + a_2 w_i(\phi_2) + \dots + a_k w_i(\phi_k) \succ b)$$

$$\Rightarrow (a_1 w_j(\phi_1) + \dots + a_k w_j(\phi_k) \succ b).$$

proof.

The proof goes very much like this, if objectivity holds, then all the agents will have the same probability distribution in a state $s \in S$. and hence above formula must hold for each $s \in S$.

If the above formula ~~must~~ holds for all agents i and j , then objectivity must hold.

[detail of the proof can be worked out easily].

③ Uniformity corresponds to the axiom

$\phi \Rightarrow (w_i(\phi) = 1)$ if ϕ is an i -probability formula or the negation of an i -probability formula.

Proof. First we will prove that

$(M, s) \models \phi \Rightarrow (w_i(\phi) = 1)$ if uniformity holds in M .

i.e. $(M, s) \models \phi$

Then

$(M, s) \models w_i(\phi) = 1$.

i.e. $\mu_{i,s}(\{t \in S_{i,s} / (M, t) \models \phi\}) = 1$.

i.e. ϕ is true in all the states of $S_{i,s}$.

Now since uniformity holds in M , agent i will have the same probability distribution in all the states of $S_{i,s}$ and since ϕ is true in s , ϕ must be true in all the states of $S_{i,s}$.

$\therefore (M, s) \models w_i(\phi) = 1$.

Now we try to prove that

if

$$(M, s) \models \phi \Rightarrow (w_i(\phi) = 1),$$

then

uniformity holds in M .

$$(M, s) \models \phi \Rightarrow (w_i(\phi) = 1)$$

i.e

if $(M, s) \models \phi$, then

ϕ is true in all the states of $S_{i,s}$.
i.e agent i will have the same probability distribution in all the states of $S_{i,s}$.

Now since s and i are arbitrary.
uniformity holds in M .

④ SDP corresponds to the axiom:
 $\phi \Rightarrow K_i \phi$ if ϕ is an i -probability
 formula or the negation of an
 i -probability formula.

proof. First we try to prove if SDP holds
 in M and if
 $(M, s) \models \phi$.

then $(M, s) \models K_i \phi$.

Now since SDP holds, agent i will
 have the same probability distribu-
 -tion in all the states of
 $S_i(s)$.

Since ϕ is true in s , it must be
 true in all the states of $S_i(s)$.

i.e. $(M, s) \models K_i \phi$.

Now we try to proof if
 $(M, s) \models \phi \Rightarrow K_i \phi$,
 then \forall SDP holds in M .

[The above proof is
 very much similar
 to proof ③ and
 can be worked
 out easily].

Complete Axiomatizations

We now describe a natural complete axiomatizations for the logic of probability and knowledge.

I. Axioms and rule for reasoning about knowledge.

$$K1. (Ki\phi \wedge Ki(\phi \Rightarrow \psi)) \Rightarrow Ki\psi$$

$$K2. Ki\phi \Rightarrow \phi$$

$$K3. Ki\phi \Rightarrow KiKi\phi$$

$$K4. \sim Ki\phi \Rightarrow Ki\sim Ki\phi.$$

R1. From ϕ infer $Ki\phi$ (Knowledge generalization)

II Axioms for reasoning about probabilities.

$$W1. Wi(\phi) \geq 0 \text{ (nonnegativity)}$$

$$W2. Wi(\text{true}) = 1 \text{ (The probability of the event true is 1)}$$

$$W3. Wi(\phi \wedge \psi) + Wi(\phi \wedge \sim \psi) = Wi(\phi) \text{ (additivity)}$$

$$W4. Wi(\phi) = Wi(\psi) \text{ if } \phi \Leftrightarrow \psi \text{ is a propositional tautology (distributivity)}$$

$$W5. Wi(\text{false}) = 0. \text{ (The probability of the event false is 0)}$$

Theorem AX_{MEAS} is a sound and complete axiomatization for the logic of knowledge and probability.

Before proving the above theorem we give one definition and prove one lemma.

An n-atom is a formula of the form $p_1' \wedge p_2' \wedge \dots \wedge p_n'$ where p_i' is either p_i or $\sim p_i$ for each i .

Lemma. Let ϕ be a propositional formula. Assume that $\{p_1, p_2, \dots, p_n\}$ includes all of the primitive propositions that appear in ϕ . Let $At_n(\phi)$ consist of all the n-atoms δ such that $\delta \Rightarrow \phi$ is a propositional tautology. Then

$$w(\phi) = \sum_{\delta \in At_n(\phi)} w(\delta) \text{ is provable.}$$

proof. We show by induction on $j \geq 1$ that if $\psi_1, \psi_2, \dots, \psi_{2j}$ are all of the j -atoms, then

$w(\phi) = w(\phi \wedge \psi_1) + \dots + w(\phi \wedge \psi_{2j})$ is provable.

If $j=1$, this follows by finite additivity (axiom W3).

Assume inductively, we have shown that

$w(\phi) = w(\phi \wedge \psi_1) + \dots + w(\phi \wedge \psi_{2j})$ is provable.

By W3.

$$\begin{aligned} w(\phi \wedge \psi_1 \wedge p_{j+1}) + w(\phi \wedge \psi_1 \wedge \sim p_{j+1}) \\ = w(\phi \wedge \psi_1) \text{ is provable.} \end{aligned}$$

Therefore we can replace each

$$w(\phi \wedge \psi_r) \text{ by } w(\phi \wedge \psi_r \wedge p_{j+1}) + w(\phi \wedge \psi_r \wedge \sim p_{j+1})$$

This proves the inductive step.

In particular

$w(\phi) = w(\phi \wedge \delta_1) + \dots + w(\phi \wedge \delta_{2n})$ is provable.

Since $\{p_1, \dots, p_n\}$ includes all of the primitive propositions that appear in ϕ , if $\delta_r \in \text{Atn}(\phi)$, then $\phi \wedge \delta_r \equiv \delta_r$.

because
 if $\phi \wedge \delta_r$ is true, then δ_r must be true and if δ_r is true then ϕ must be true, since $\delta_r \Rightarrow \phi$ is a propositional tautology.

If $\delta_r \notin \text{Atn}(\phi)$, then $\phi \wedge \delta_r \equiv \text{false}$.

So by W4, we see that if $\delta_r \in \text{Atn}(\phi)$ then $w(\phi \wedge \delta_r) = w(\delta_r)$ is provable.

and if $\delta_r \notin \text{Atn}(\phi)$ then $w(\phi \wedge \delta_r) = w(\text{false})$ is provable.

\therefore we can replace each $w(\phi \wedge \delta_r)$ by either $w(\delta_r)$ or $w(\text{false})$. Also we can drop the $w(\text{false})$ terms, since $w(\text{false}) = 0$ is provable.

The lemma now follows.

Proof of The main Theorem:

Soundness is straightforward, so we focus on completeness.

In order to show completeness we need to show that if the formula ϕ is consistent, then ϕ is satisfiable in a Kripke structure for knowledge and probability satisfying MEAS.

Let $\text{sub}(\phi)$ be the set of all subformulas of ϕ and $\text{sub}^+(\phi)$ be the set of all subformulas of ϕ and their negations.

Let s be the finite set of formulas and let ϕ_s be the conjunction of the formulas in s . We say that s is consistent if it is not the case that $AX_{\text{MEAS}} \vdash \sim \phi_s$

The set s is a maximal consistent subset of $\text{sub}^+(\phi)$ if it is consistent, a subset of $\text{sub}^+(\phi)$ and for every subformula ψ of ϕ includes one of ψ or $\sim \psi$.

We now construct a Kripke structure for knowledge (but not probability) $(S, \pi, \mathcal{K}_1, \mathcal{K}_2, \dots, \mathcal{K}_n)$ as follows.

We take S , the set of states to consist of all maximal consistent subsets of $\text{sub}^+(\emptyset)$. If s and t are states ~~that~~ then

$(s, t) \in \mathcal{K}_i$ iff s and t contains the same formula of the type $\mathcal{K}_i \psi$

We define π so that for a primitive proposition p , we have $\pi(s)(p) = \text{true}$ iff p is one of the formulas in the set s .

Our goal is to define a probability assignment \mathcal{P} such that if we consider the Kripke structure for knowledge and probability

$M = (S, \pi, \mathcal{K}_1, \dots, \mathcal{K}_n, \mathcal{P})$, then for every state $s \in S$ and every formula $\psi \in \text{sub}^+(\emptyset)$

$(M, s) \models \psi$ iff $\psi \in s$.

Now we have

$$w_i(\psi) = \sum_{s \in S / \psi \in s} w_i(\phi_s)$$

is provable in
AXMEAS.

(This follows from
the above lemma)

Hence we can show that any i -probability
formula $\psi \in \text{Sub}^+(\Phi)$ is provably
equivalent to a formula of the form

$$\sum_{s \in S} c_s w_i(\phi_s) \gg b \text{ for some appropriate coefficient } c_s.$$

Fix an agent i and state $s \in S$.
Assume that ψ is equivalent to

$$\sum_{s' \in S} c_{s'} w_i(\phi_{s'}) \gg b.$$

Since s is maximal consistent set
either ψ or $\sim \psi \in s$.

If $\psi \in s$. Then the corresponding
inequality is

$$\sum_{s' \in S} c_{s'} \mu_{i,s} \{ t \in S_{i,s} / (M,t) \models \phi_{s'} \} \gg b$$

But since s' is the maximal consistent set. $\phi_{s'}$ is true in s' only.

$$\sum_{s' \in S} c_{s'} \mu_{i,s}(s') \geq b.$$

Here the summation is for all states $s' \in S$, but I think it should not be for all the states.

(But here how we know that either s' is present in $S_{i,s}$ or not. If $S_{i,s} = S$, then it is O.K.)

Example

We take an i -probability formula

$$w_i(\psi_1) + w_i(\psi_2) + \dots + w_i(\psi_n) \geq b.$$

But how do we confirm that in each state $s' \in S$ one of $\psi_1, \psi_2, \dots, \psi_n$ is present.

Finally we have the inequality

$$\sum_{s' \in S} \mu_{i,s}(s') = 1.$$

This set of linear equality and inequalities has a solution.

For each i and s , we solve the corresponding set of inequalities separately.

We now define \mathcal{P} so that $\mathcal{P}_{i,s} = (S, 2^S, \mu_{i,s})$ where if $A \subseteq S$, then

$$\mu_{i,s}(A) = \sum_{s' \in A} \mu_{i,s}(s').$$

Now we want to show that for every subformula ψ of $\text{Sub}^+(\emptyset)$ and every state in s , we have

$$(M, s) \models \psi \quad \text{iff} \quad \psi \in s.$$

The proof proceeds by induction on ψ . If ψ is primitive proposition, the result is immediate from the definition of π . The case where ψ is a negation or conjunction are straightforward.

Now if ψ is an i -probability formula
then suppose

$$(M, \mathcal{S}) \vDash \psi$$

suppose ψ is of the
form

Then

$$w_i(\psi_1) + w_i(\psi_2) \geq b.$$

$$(M, \mathcal{S}) \vDash w_i(\psi_1) + w_i(\psi_2) \geq b.$$

iff

$$\mu_{i, \mathcal{S}}(\{t \in S_{i, \mathcal{S}} \mid (M, t) \vDash \psi_1\})$$

$$+ \mu_{i, \mathcal{S}}(\{t \in S_{i, \mathcal{S}} \mid (M, t) \vDash \psi_2\}) \geq b.$$

$$\equiv \sum_{\substack{t \in S_{i, \mathcal{S}} \\ (M, t) \vDash \psi_1}} \mu_{i, \mathcal{S}}(t) + \sum_{\substack{t \in S_{i, \mathcal{S}} \\ (M, t) \vDash \psi_2}} \mu_{i, \mathcal{S}}(t) \geq b.$$

which confirms that $\psi \in \mathcal{S}$.

The proof of the opposite side is
same as above.

Now suppose ψ is of the form

$$K_i \psi'$$

$K_i \psi' \in \mathcal{S}$. Then for all $t \in \mathcal{I}_i(\mathcal{S})$

$$K_i \psi' \in t.$$

Now since t is maximal consistent
set, either $\psi' \in t$ or $\sim \psi' \in t$.

Now from $K3$

$$\psi' \in t.$$

By the induction hypothesis

$$(M, t) \models \psi'$$

$$\text{i.e. } (M, s) \models K_i \psi'.$$

Now suppose that

$$(M, s) \models K_i \psi'$$

Let s_i be the subset of s consisting of all the formulas in s of the form $K_i \psi''$ or $\sim K_i \psi''$.

s_i includes one of $K_i \psi'$ or $\sim K_i \psi'$. We plan to show that in fact it must include $K_i \psi'$.

We claim that

$$A \times_{MEAS} \vdash \phi_{s_i} \Rightarrow \psi' \quad \text{--- } \textcircled{1}$$

For suppose that,

then $\phi_{s_i} \wedge \sim \psi'$ is consistent, then there is a maximal consistent set t which includes $s_i \cup \sim \psi'$.

Then we have $(s, t) \in \mathcal{I}_i$ and by induction hypothesis $(M, t) \models \sim \psi'$ which contradicts our assumption $(M, s) \models K_i \psi'$.

Thus ① holds.

By R1 from ①, we have

$$AX_{MEAS} \vdash Ki(\phi_{si} \Rightarrow \psi') \quad \text{--- ②}$$

Using K1 we get

$$AX_{MEAS} \vdash Ki\phi_{si} \Rightarrow Ki\psi' \quad \text{--- ③}$$

Every conjunct of ϕ_{si} is of the form $Ki\psi''$ or $\sim Ki\psi''$. Thus if σ is one of the conjuncts of ϕ_{si} using either K3 or K4

$$AX_{MEAS} \vdash \sigma \Rightarrow Ki\sigma. \quad \text{--- ④}$$

It is well known that for any formulas σ_1 and σ_2

$$AX_{MEAS} \vdash Ki(\sigma_1 \wedge \sigma_2) \Leftrightarrow Ki\sigma_1 \wedge Ki\sigma_2$$

Thus from ④ it follows that

$$AX_{MEAS} \vdash \phi_{si} \Rightarrow Ki\phi_{si} \quad \text{--- ⑤}$$

from ③ and ⑤ it follows that

$$AX_{MEAS} \vdash \phi_{si} \Rightarrow Ki\psi'$$

since ϕ_s and hence ϕ_{si} is consistent it now follows that $\neg Ki\psi'$ cannot be one of the

conjunctions of ϕ_{si} , hence $K\psi' \in S$.

If ϕ is consistent it must be in one of the maximal consistent subsets of $\text{sub}^+(\phi)$.

Thus it follows that if ϕ is consistent then it must be satisfiable in the structure M .

This completes the proof.

Probability Assignment in Linear Time Temporal Logic.

In order to give semantics to such formulas, we first need to review briefly some probability theory.

A probability space is a tuple (S, \mathcal{K}, μ) where S is a set of states, \mathcal{K} is a σ -algebra of subsets of S , and μ is a probability measure defined on the measurable sets.

A probability structure is a tuple $M = (S, \mathcal{K}, \mu, \pi)$ where (S, \mathcal{K}, μ) is a probability space and π associates with each state in S a truth assignment on the primitive propositions in ϕ .

Syntax

We fix a countable set of atomic propositions $P = \{p_0, p_1, \dots\}$.

Then ϕ , the set of formulas is defined inductively as follows

- Every member of P belongs to ϕ .
- If α and β are formulas in ϕ , then so are $\neg\alpha$, $\alpha \vee \beta$, $\bigcirc\alpha$, $\alpha \cup \beta$, $w(\alpha)$.

Semantics

A model is a function $M: N_0 \rightarrow 2^S$. In other words, a model is an infinite sequence $\langle S_0, S_1, \dots \rangle$ of subsets of S .

We write

$\mathcal{P}, M, i \models \alpha$ to denote that " α is true at time instant i in the model M for probability structure \mathcal{P} ."

This notion is defined inductively according to the structure of α .

- $\mathcal{P}, M, i \models \beta$, where $\beta \in \mathcal{P}$
iff
 $\forall s \in M(i) \quad \pi(s)(\beta) = T$.
- $\mathcal{P}, M, i \models \sim \alpha$ iff
 $\mathcal{P}, M, i \not\models \alpha$.
- $\mathcal{P}, M, i \models \alpha \vee \beta$ iff
 $\mathcal{P}, M, i \models \alpha$ or $\mathcal{P}, M, i \models \beta$.
- $\mathcal{P}, M, i \models O\alpha$ iff
 $\mathcal{P}, M, i+1 \models \alpha$.
- $\mathcal{P}, M, i \models \alpha \cup \beta$ iff
There exist $k > i$ such that
 $\mathcal{P}, M, k \models \beta$ and for all j such
that $i \leq j < k$ $\mathcal{P}, M, j \models \alpha$.

$$\mathcal{P}, M, i \models w(\alpha) \gg b$$

iff

$$\mu(\{t \in M(i) \mid (M, t) \models \alpha\}) \gg b.$$

$\mathcal{P}, M, i \models \Diamond \alpha$ iff there exist $k \gg i$ such that

$$\mathcal{P}, M, k \models \alpha.$$

$\mathcal{P}, M, i \models \Box \alpha$ iff $\forall k \gg i$

$$\mathcal{P}, M, k \models \alpha.$$

Now we take certain examples so that it becomes more clear.

When we say

$$\mathcal{P}, M, i \models \neg w(\Box \alpha) \gg b.$$

$$\mathcal{P}, M, i \models w(\Box \alpha) \gg b$$

iff

$$\mu(\{t \in M(i) \mid (M, t) \models \Box \alpha\}) \gg b.$$

Now ~~when~~ we say $\Box \alpha$ is true at instant i in state t in model M

iff $t \in M(i)$ and

$$M, \overset{k}{t} \models \alpha \quad \forall k \gg i$$

When we say

$$P, M, i \models \Box (w(\alpha) \gg b)$$

$$P, M, i \models \Box (w(\alpha) \gg b)$$

iff

$$P, M, K \models w(\alpha) \gg b \quad \forall K \gg i$$

and we already know

when

$$P, M, K \models w(\alpha) \gg b.$$

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